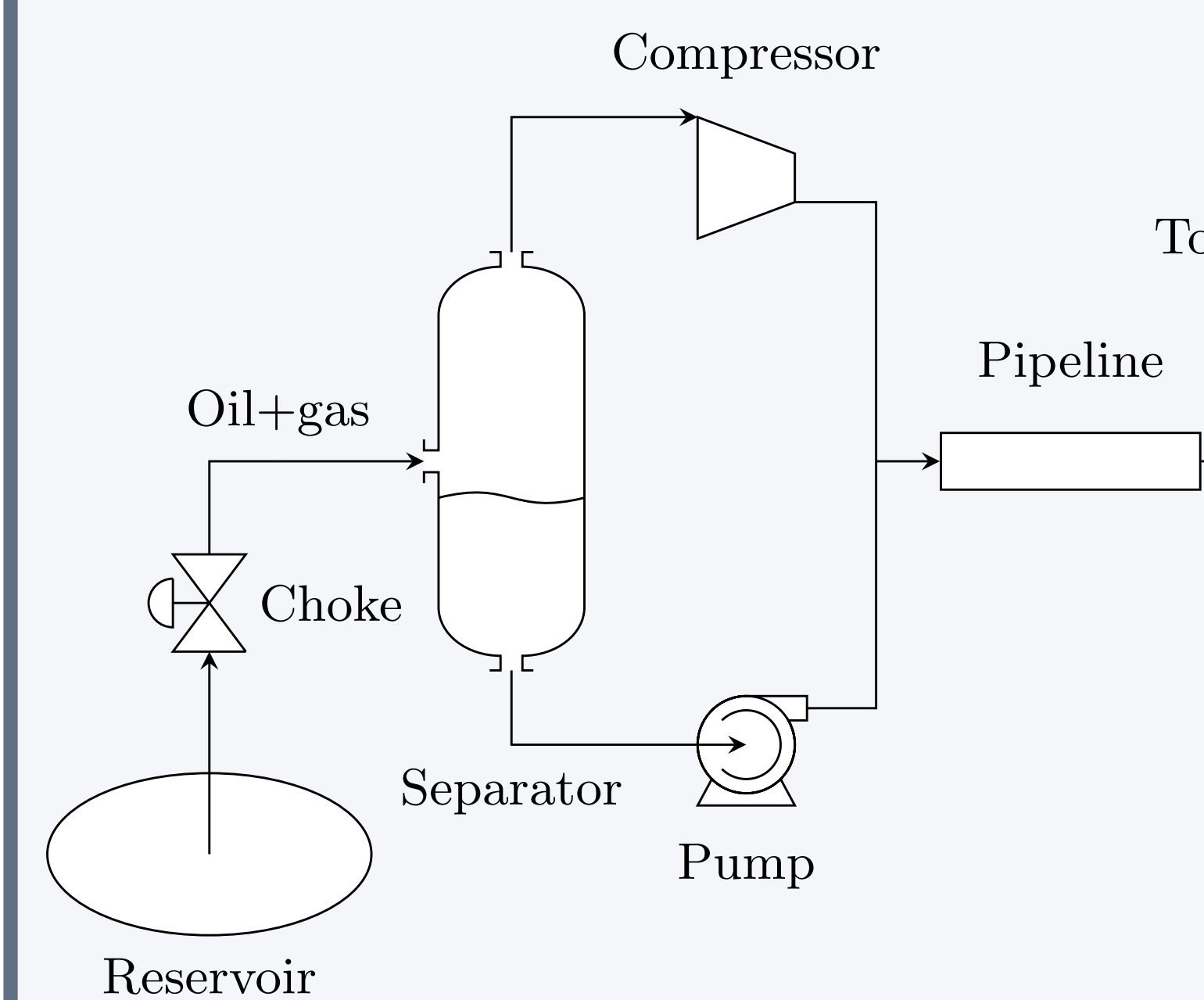


## Abstract

Subsea systems operate in harsh environments and under large uncertainties. Because they are very difficult and expensive to access, an optimal operational strategy must maximize profit, and at the same time ensure that no unplanned shutdowns occur. To achieve this, we consider a min-max robust optimization approach and a scenario-based optimization approach with recourse. Although both methods avoid unplanned shutdowns, the scenario-based method results in a less conservative solution at the cost of a larger problem size.

## Process description



**Figure 1:** Process diagram of the subsea gas compression station.

### Degradation of the compressor

- Result of wear and shock damage (due to setpoint changes  $\Delta N$ )
- Change in health is a function of compressor speed  $N$

$$\Delta h = - \left( \underbrace{p_N N^3}_{\text{Wear and tear}} + \underbrace{p_{\Delta} |\Delta N|^3}_{\text{Shock damage}} \right) \quad (1)$$

**Challenge:** trade-off between degradation and production maximization.

## Conclusion

- Prognostics and control can be combined to obtain a control structure that gives economical and safe operation
- Robustness towards uncertainty is important: must solve a stochastic optimization problem
- Scenario-based method less conservative than worst-case approach, without jeopardizing integrity

**Future work** will focus on measurement feedback and state estimation, more detailed degradation models and extension to system-wide health-aware operation.

## Combining prognostics and control

Objective: maximize expected net present value of gas production while keeping compressor healthy

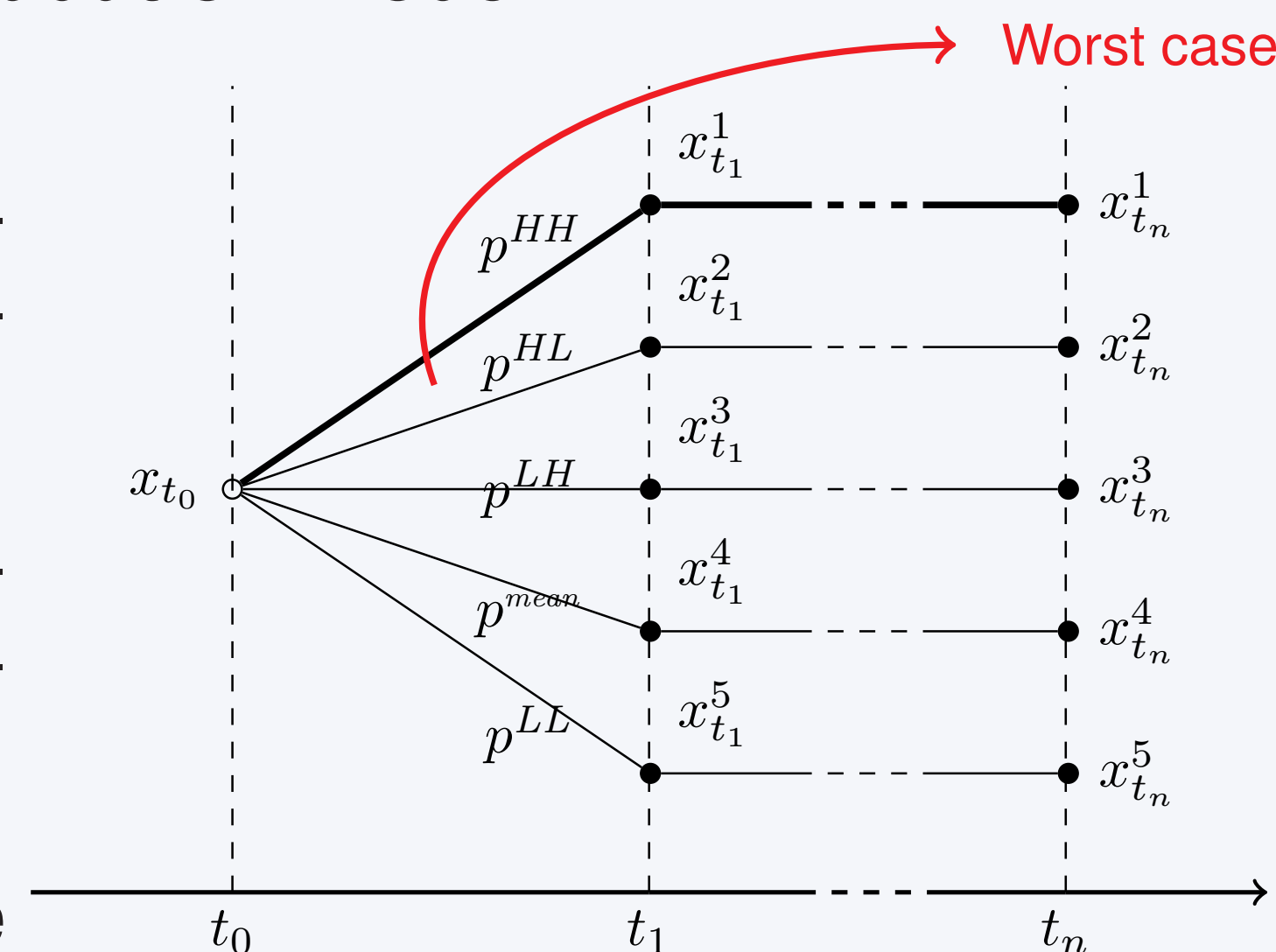
$$\min_{\mathbf{u}} \quad \mathbb{E} \left( - \int_0^{t_f} \text{NPV}(\dot{m}_{gas}) dt \right) \quad \text{s.t.} \quad \begin{cases} \text{Process constraints} \\ \text{Health constraints} \end{cases} \quad (2)$$

$\mathbf{u}$  : inputs (choke and compressor speed),  $\mathbf{p}$  : uncertain degradation parameters:  $p_N$  and  $p_{\Delta}$

### Handling uncertainty in degradation model:

Comparison of three methods:

1. Nominal case: Uncertainty not handled explicitly
2. Worst case: Worst possible realization of parameters
3. Scenario-based: Use five scenarios to approximate uncertainty distribution



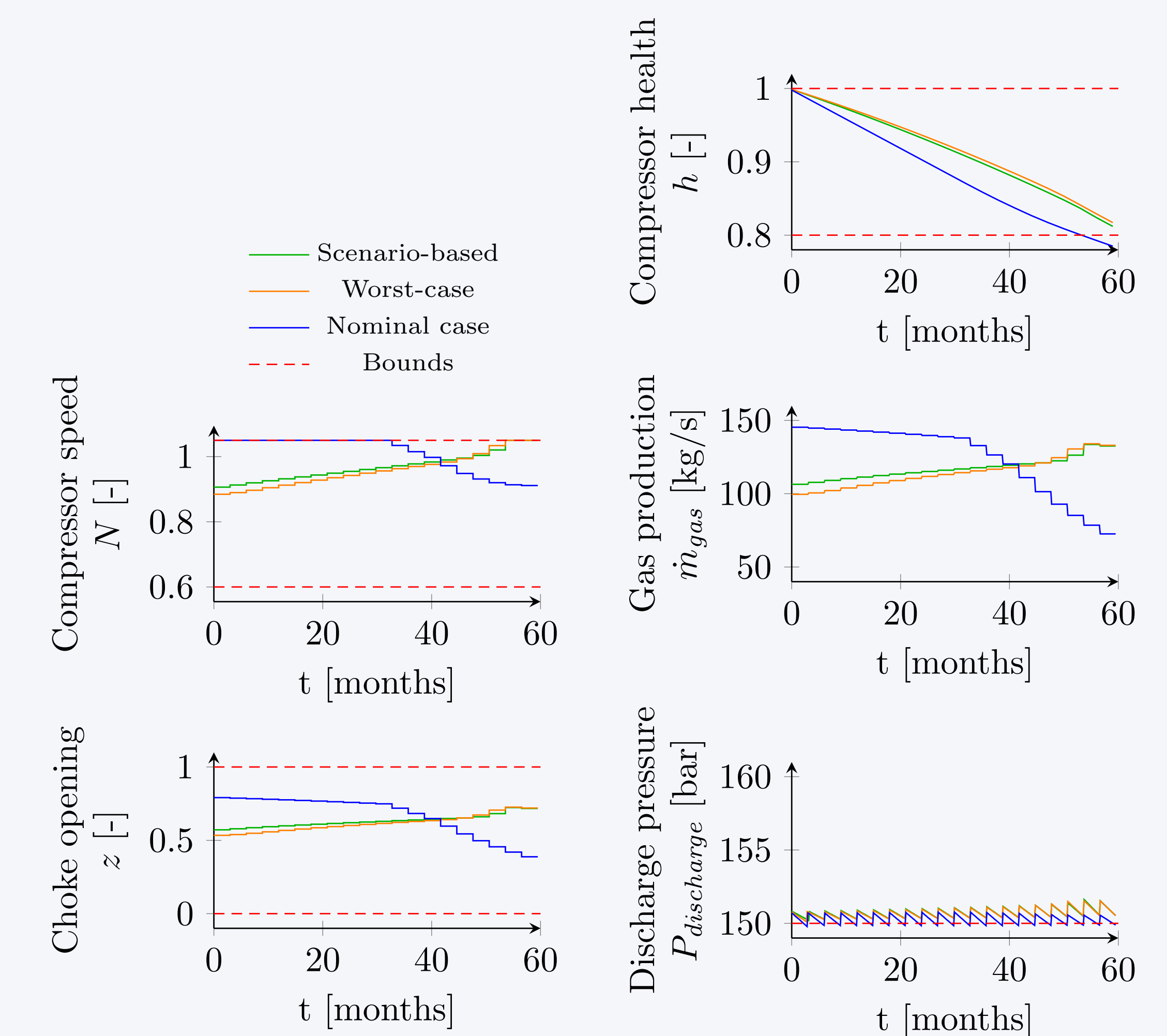
**Figure 2:** Process diagram of the subsea gas compression station.

**Table 1:** Values of the uncertain variables  $p_N$  and  $p_{\Delta N}$  in the scenarios used to generate the scenario tree.

Scenario	$p_N$	$p_{\Delta N}$
LL	0.006 ( $\mu - 2\sigma$ )	0.6 ( $\mu - 2\sigma$ )
LH	0.006 ( $\mu - 2\sigma$ )	1.8 ( $\mu + 2\sigma$ )
HL	0.018 ( $\mu + 2\sigma$ )	0.6 ( $\mu - 2\sigma$ )
HH	0.018 ( $\mu + 2\sigma$ )	1.8 ( $\mu + 2\sigma$ )
mean	0.012 ( $\mu$ )	1.2 ( $\mu$ )

## Results

- Scenario-based method outperforms the worst-case method
- Nominal case: health constraint and discharge pressure constraint are violated



**Figure 3:** Comparison of closed-loop performance of three different controllers in the presence of uncertainty. The realizations of the uncertain variables are  $p_N = 0.015$  and  $p_{\Delta} = 1.5$ .

**Table 2:** Normalized profit, i.e. net present gas production, for the three methods (in closed-loop).

Method	Discounted closed-loop profit
Scenario-based	1.026
Worst-case	1.000
Nominal case	1.056*

\* Constraint violation

## References

- [1] Sergio Lucia, Sankaranarayanan Subramanian, and Sebastian Engell. Non-conservative robust nonlinear model predictive control via scenario decomposition. In *Control Applications (CCA), 2013 IEEE International Conference on*, pages 586–591. IEEE, 2013.
- [2] T Escobet, V Puig, and F Nejjari. Health aware control and model-based prognosis. In *Control & Automation (MED), 2012 20th Mediterranean Conference on*, pages 691–696. IEEE, 2012.
- [3] Eduardo Bento Pereira, Roberto Kawakami Harrop Galvão, and Takashi Yoneyama. Model Predictive Control using Prognosis and Health Monitoring of actuators. In *Industrial Electronics (ISIE), 2010 IEEE International Symposium on*, pages 237–243. IEEE, 2010.
- [4] Jean C Salazar, Philippe Weber, Fatiha Nejjari, Didier Theilliol, and Ramon Sarrate. MPC Framework for System Reliability Optimization. In *Advanced and Intelligent Computations in Diagnosis and Control*, pages 161–177. Springer, 2016.